

Introduction to Machine Translation and Phrase-Based Machine Translation

Aleš Tamchyna

Charles University in Prague

September 8, 2015

Other Approaches to Machine Translation

Our topic: **phrase-based MT**.

(Some) other approaches:

- Neural networks.

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Thursday 9:00: Deep Syntactic MT and TectoMT (Martin Popel)

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- Deep (dependency) syntax.
Thursday 9:00: Deep Syntactic MT and TectoMT (Martin Popel)
- Constituency syntax.
Friday 13:30: Syntax Extraction and Decoding (Hieu Hoang)

Where to Find More?

Books:

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Books:



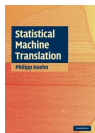
Ondřej Bojar: Čeština a strojový překlad

Where to Find More?

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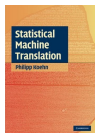
Philipp Koehn: Statistical Machine Translation

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Online:

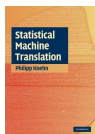
- <http://www.statmt.org/>

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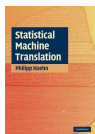
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Online:

- <http://www.statmt.org/>
- <http://www.statmt.org/moses/>
- <http://mttalks.ufal.cz/>

Probability – Quick Refresher

- $P(A) \in [0, 1]$... Probability of event A .

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Given that I see clouds (B), what is the chance it will rain today (A)?

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$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

Probability – Quick Refresher

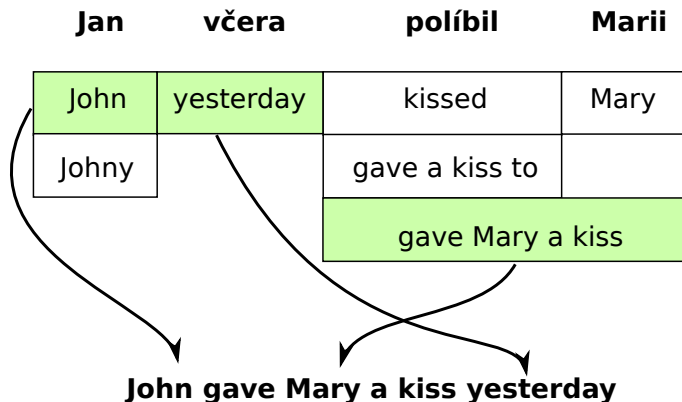
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Given that I see clouds (B), what is the chance it will rain today (A)?

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

- Bayes' Theorem (inverse probability):

$$P(B|A) = \frac{P(A|B)P(B)}{P(A)}$$

Our Goal: Phrase-Based Machine Translation



The Essential Ingredient



Our Own Parallel Corpus

žlutý

the

byl

parrot

žlutý

yellow

ten

was

pes

dog

papoušek

yellow

Our Own Parallel Corpus

žlutý

the

byl

parrot

žlutý

yellow

ten

was

pes

dog

papoušek

yellow

What does "žlutý" mean in English?

Our Own Parallel Corpus

žlutý

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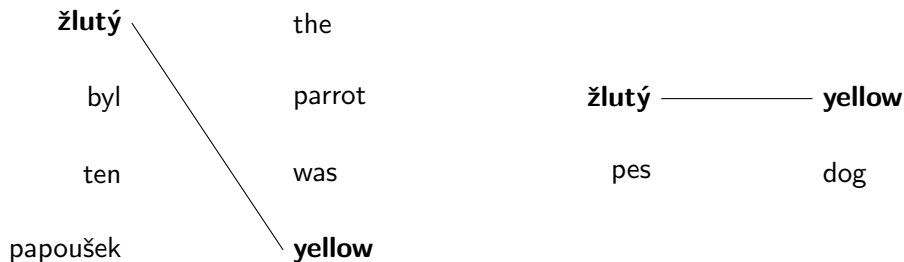
dog

papoušek

yellow

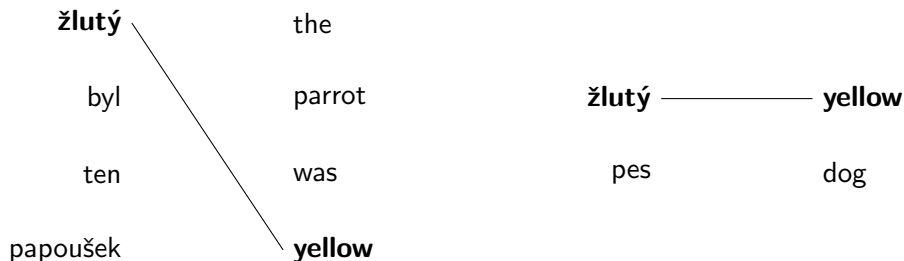
What does "žlutý" mean in English?

Our Own Parallel Corpus



What does "žlutý" mean in English?

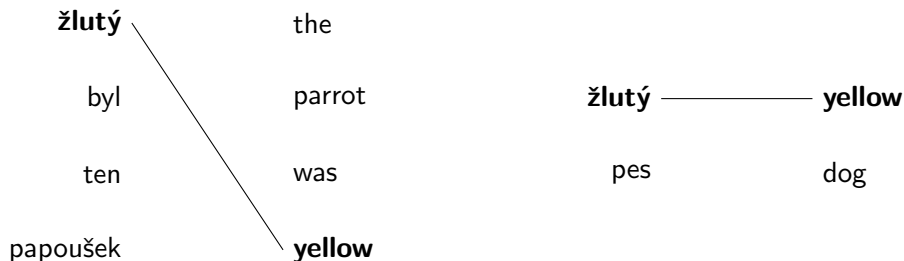
Our Own Parallel Corpus



What does "žlutý" mean in English?

We used the data to **infer an alignment** between the words.

Our Own Parallel Corpus

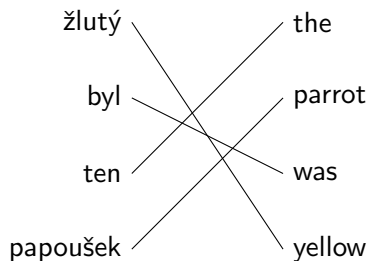


What does "žlutý" mean in English?

We used the data to **infer an alignment** between the words.
Given the alignment, we could find the most probable translation.

Estimating Translation Probability

If we had the alignment:

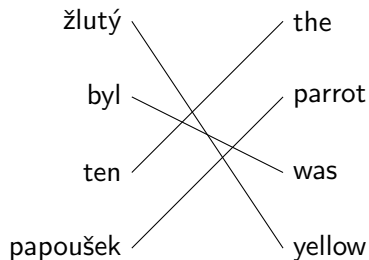


žlutý yellow
pes dog

$$P(\text{"yellow" | "žlutý"}) = \frac{c(\text{yellow} \rightarrow \text{žlutý})}{c(\text{žlutý})} = \frac{2}{2} = 1$$

Estimating Translation Probability

If we had the alignment:



žlutý yellow

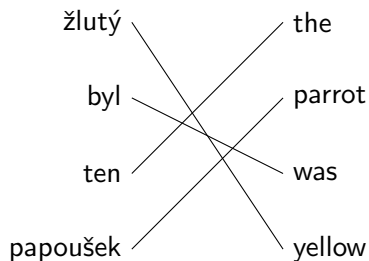
pes dog

$$P(\text{"yellow"} | \text{"žlutý"}) = \frac{c(\text{yellow} \rightarrow \text{žlutý})}{c(\text{žlutý})} = \frac{2}{2} = 1$$

$$P(* | \text{"žlutý"}) = 0$$

Estimating Translation Probability

If we had the alignment:



žlutý ————— yellow

pes ————— dog

$$P(\text{"yellow"} | \text{"žlutý"}) = \frac{c(\text{yellow} \rightarrow \text{žlutý})}{c(\text{žlutý})} = \frac{2}{2} = 1$$

$$P(* | \text{"žlutý"}) = 0$$

We will align the English words to Czech words.

Estimation of IBM Model 1

žlutý

the

byl

parrot

žlutý

yellow

ten

was

pes

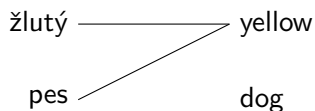
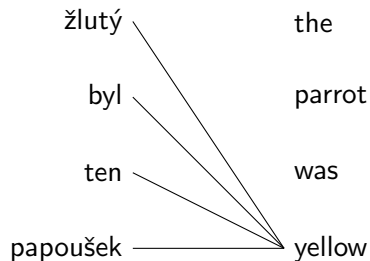
dog

papoušek

yellow

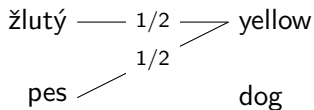
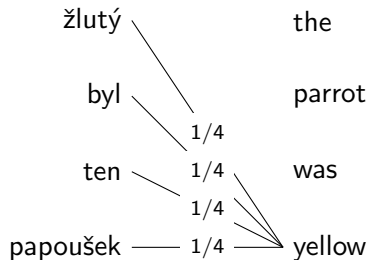
Our approach: distribute our one alignment link among all words.

Estimation of IBM Model 1



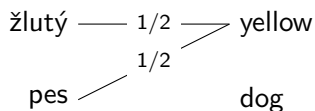
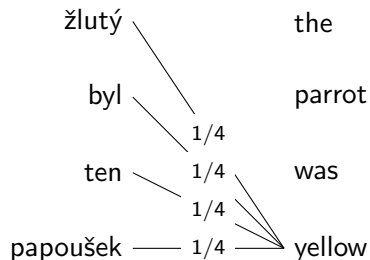
How to weight these "partial" links? Use translation probability $P(\mathbf{e}|\mathbf{f})$.

Estimation of IBM Model 1



Initially, we don't know anything \Rightarrow start with uniform estimates.

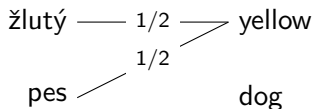
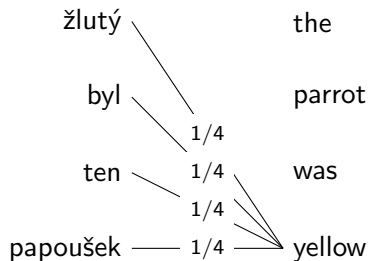
Estimation of IBM Model 1



Let's sum up the evidence that "yellow" aligns to "žlutý":

$$c(\text{yellow} \rightarrow \text{žlutý}) = 1/4 + 1/2 = 3/4$$

Estimation of IBM Model 1



...and the evidence that "yellow" aligns to other words...

$$c(\text{yellow} \rightarrow \text{žlutý}) = 3/4$$

$$c(\text{yellow} \rightarrow \text{byl}) = 1/4$$

$$c(\text{yellow} \rightarrow \text{ten}) = 1/4$$

$$c(\text{yellow} \rightarrow \text{papoušek}) = 1/4$$

$$c(\text{yellow} \rightarrow \text{pes}) = 1/2$$

Estimation of IBM Model 1



...and do the same for the other "partial" alignment links...

$c(\text{yellow} \rightarrow \text{žlutý}) = 3/4, c(\text{yellow} \rightarrow \text{byl}) = 1/4, \dots$

$c(\text{was} \rightarrow \text{žlutý}) = 1/4, c(\text{was} \rightarrow \text{byl}) = 1/4, \dots$

Estimation of IBM Model 1



...and do the same for the other "partial" alignment links...

$c(\text{yellow} \rightarrow \text{žlutý}) = 3/4$, $c(\text{yellow} \rightarrow \text{byl}) = 1/4$, ...

$c(\text{was} \rightarrow \text{žlutý}) = 1/4$, $c(\text{was} \rightarrow \text{byl}) = 1/4$, ...

$c(\text{parrot} \rightarrow \text{žlutý}) = 1/4$, $c(\text{parrot} \rightarrow \text{byl}) = 1/4$, ...

Estimation of IBM Model 1



...and do the same for the other "partial" alignment links...

$c(\text{\textit{yellow}} \rightarrow \text{\textit{\u017e}lut\u016f}) = 3/4, c(\text{\textit{yellow}} \rightarrow \text{\textit{byl}}) = 1/4, \dots$

$c(\text{\textit{was}} \rightarrow \text{\textit{\u017e}lut\u016f}) = 1/4, c(\text{\textit{was}} \rightarrow \text{\textit{byl}}) = 1/4, \dots$

$c(\text{\textit{parrot}} \rightarrow \text{\textit{\u017e}lut\u016f}) = 1/4, c(\text{\textit{parrot}} \rightarrow \text{\textit{byl}}) = 1/4, \dots$

$c(\text{\textit{the}} \rightarrow \text{\textit{\u017e}lut\u016f}) = 1/4, c(\text{\textit{the}} \rightarrow \text{\textit{byl}}) = 1/4, \dots$

Estimation of IBM Model 1

žlutý

the

byl

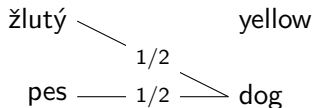
parrot

ten

was

papoušek

yellow



...and do the same for the other "partial" alignment links...

$c(\text{yellow} \rightarrow \text{žlutý}) = 3/4, c(\text{yellow} \rightarrow \text{byl}) = 1/4, \dots$

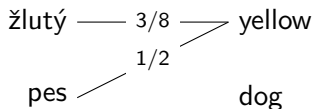
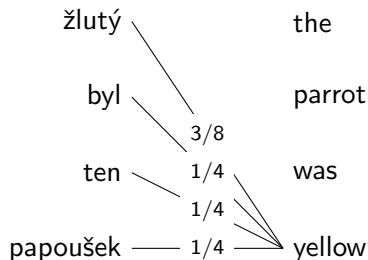
$c(\text{was} \rightarrow \text{žlutý}) = 1/4, c(\text{was} \rightarrow \text{byl}) = 1/4, \dots$

$c(\text{parrot} \rightarrow \text{žlutý}) = 1/4, c(\text{parrot} \rightarrow \text{byl}) = 1/4, \dots$

$c(\text{the} \rightarrow \text{žlutý}) = 1/4, c(\text{the} \rightarrow \text{byl}) = 1/4, \dots$

$c(\text{dog} \rightarrow \text{žlutý}) = 1/2, c(\text{dog} \rightarrow \text{pes}) = 1/2$

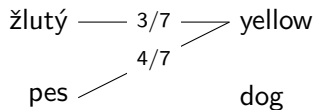
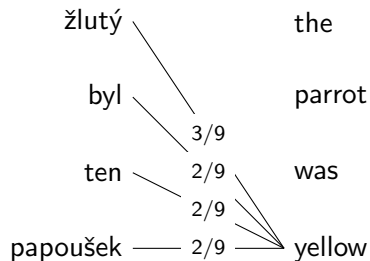
Estimation of IBM Model 1



Normalize to get the conditional probability distributions:

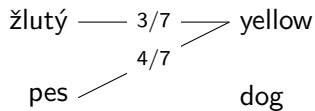
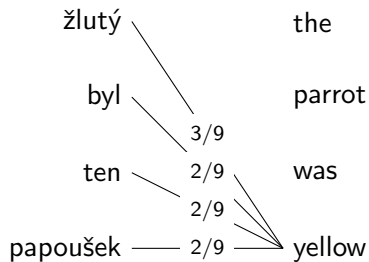
$$\begin{array}{lll} P(\text{yellow}|\text{žlutý}) = 3/8 & P(\text{yellow}|\text{byl}) = 1/4 & P(\text{yellow}|\text{pes}) = 1/2 \\ P(\text{was}|\text{žlutý}) = 1/8 & P(\text{was}|\text{byl}) = 1/4 & P(\text{was}|\text{pes}) = 0 \\ P(\text{parrot}|\text{žlutý}) = 1/8 & P(\text{parrot}|\text{byl}) = 1/4 & \dots & P(\text{parrot}|\text{pes}) = 0 \\ P(\text{the}|\text{žlutý}) = 1/8 & P(\text{the}|\text{byl}) = 1/4 & & P(\text{the}|\text{pes}) = 0 \\ P(\text{dog}|\text{žlutý}) = 2/8 & P(\text{dog}|\text{byl}) = 0 & & P(\text{dog}|\text{pes}) = 1/2 \end{array}$$

Estimation of IBM Model 1



What next? Iterate.

Estimation of IBM Model 1



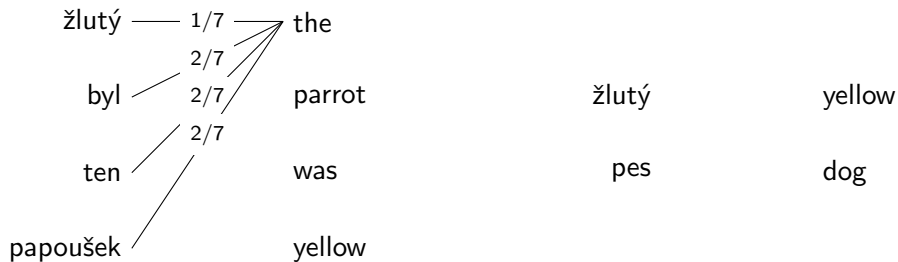
Estimation of IBM Model 1



Estimation of IBM Model 1



Estimation of IBM Model 1



Estimation of IBM Model 1

žlutý

the

byl

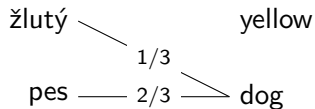
parrot

ten

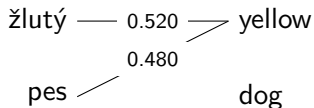
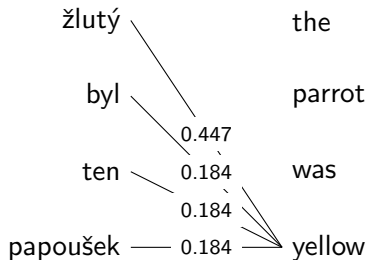
was

papoušek

yellow

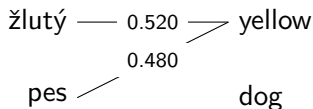
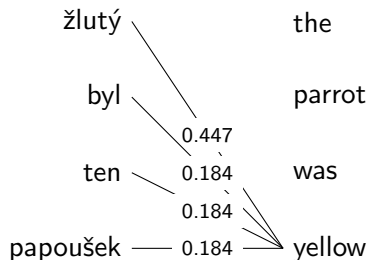


Estimation of IBM Model 1



$P(\text{yellow} \text{žlutý}) = 0.5$	$P(\text{yellow} \text{byl}) = 0.206$	$P(\text{yellow} \text{pes}) = 0.462$
$P(\text{was} \text{žlutý}) = 0.094$	$P(\text{was} \text{byl}) = 0.265$	$P(\text{was} \text{pes}) = 0$
$P(\text{parrot} \text{žlutý}) = 0.094$	$P(\text{parrot} \text{byl}) = 0.265$	$P(\text{parrot} \text{pes}) = 0$
$P(\text{the} \text{žlutý}) = 0.094$	$P(\text{the} \text{byl}) = 0.265$	$P(\text{the} \text{pes}) = 0$
$P(\text{dog} \text{žlutý}) = 0.219$	$P(\text{dog} \text{byl}) = 0$	$P(\text{dog} \text{pes}) = 0.538$

Estimation of IBM Model 1



The algorithm: expectation maximization (EM)

- 1 Initialize the model with uniform probabilities.
- 2 Apply the model to the data (**expectation** step).
- 3 Re-estimate the model from the data (**maximization** step).
- 4 Go to 2 and repeat until probabilities stop changing.

Word-Based Models

- IBM Models 1-5 (increasing model complexity)
- Brown et al. (1993): The Mathematics of Statistical Machine Translation: Parameter Estimation
- Originally developed for word-based translation
- Higher models account for:
 - ▶ word position (IBM 1 only models the lexical translation probability)
 - ▶ fertility (number of English words aligned to a foreign word)
- Today: used for **word alignment**

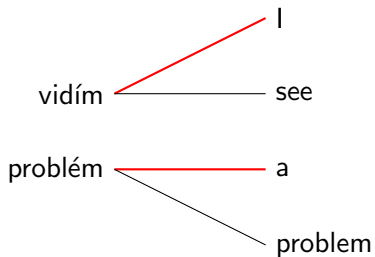
IBM Model 1

- We treat the alignment between words as a hidden variable.
- Alignment is a function; each English word (position) picks a foreign counterpart, e.g. $a(4) = 1$ ("yellow" aligns to "žlutý" in the first sentence).
- IBM Model 1 only models lexical translation probability, so formally, the probability of sentence $\mathbf{e} = (e_1, \dots, e_m)$ given $\mathbf{f} = (f_1, \dots, f_n)$ is:

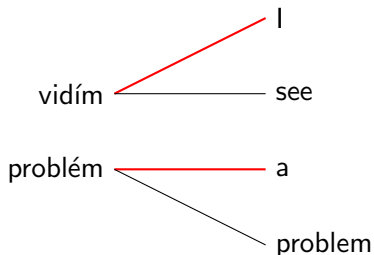
$$P(\mathbf{e}|\mathbf{f}) = \sum_{a_1=0}^n \cdots \sum_{a_m=0}^n \frac{\epsilon}{(n+1)^m} \prod_{j=1}^m t(e_j|f_{a_j}) = \frac{\epsilon}{(n+1)^m} \prod_{j=1}^m \sum_{i=0}^n t(e_j|f_i)$$

- EM finds such an alignment which maximizes the (log) likelihood of our data.

NULL Token

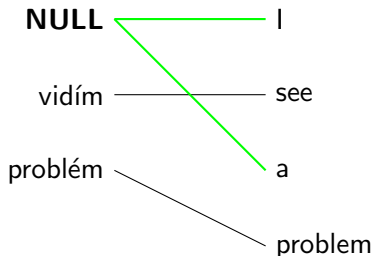


NULL Token



Do we align the indefinite article to all Czech nouns?

NULL Token



Align words which are dropped in Czech to NULL.

From IBM Models to Word Alignment

IBM models 1 to 5 are learned in a sequence; estimated parameters of one model are used to initialize the next model.

At the end of training, we can obtain the most likely alignment of the data.

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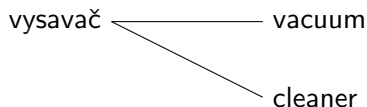
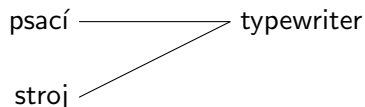
At the end of training, we can obtain the most likely alignment of the data. Alignment is a function \Rightarrow one English word cannot align to more than one foreign word.

psací	typewriter	vysavač	vacuum
stroj			cleaner

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stroj /

vysavač ————— vacuum
cleaner

There is no way that we can get this word alignment with our current models.

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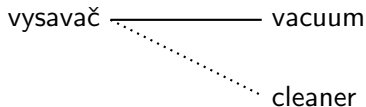
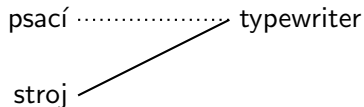
Solution: run the alignment **in both directions** (i.e., train all the models twice, English \rightarrow Czech and Czech \rightarrow English) and **symmetrize** the alignment.

Alignment Symmetrization

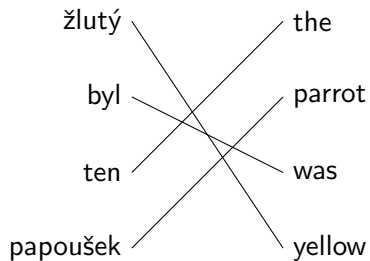
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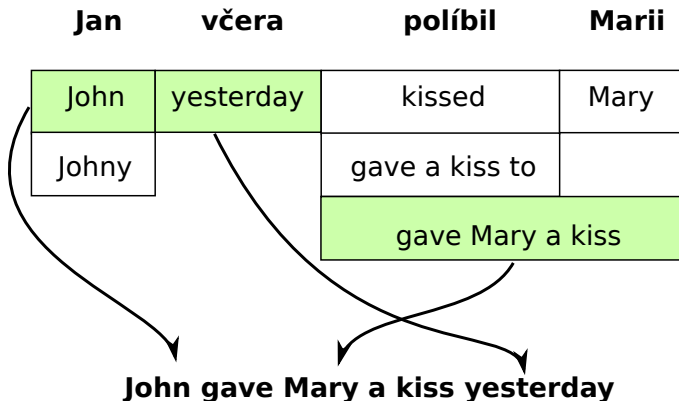
Progress Check



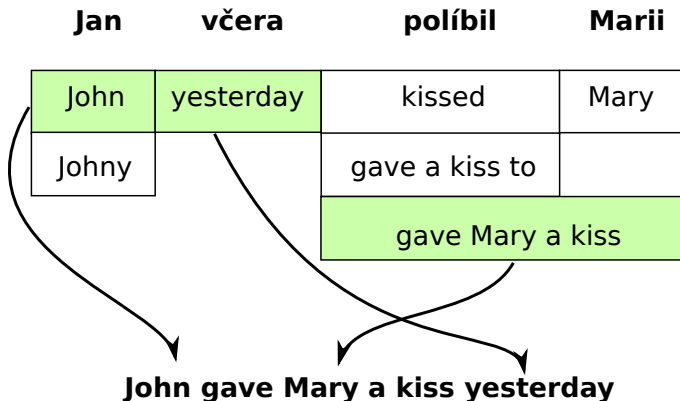
žlutý ————— yellow

pes ————— dog

Progress Check



Progress Check

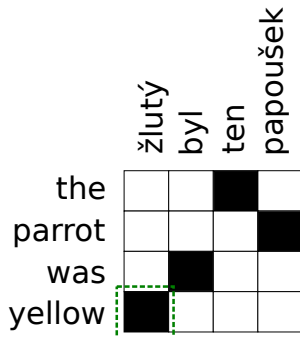


Let's go from words to phrases.

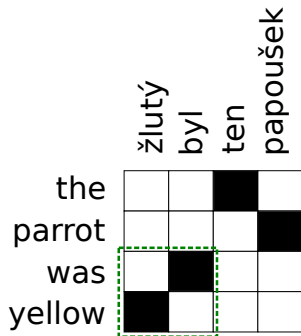
Phrase Extraction

	žlutý			
	byl			
	ten			
	papoušek			
the			■	
parrot				■
was		■		
yellow	■			

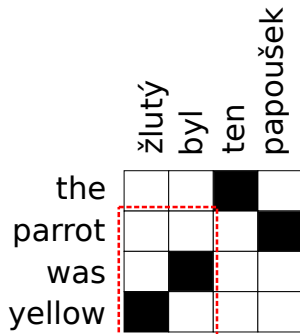
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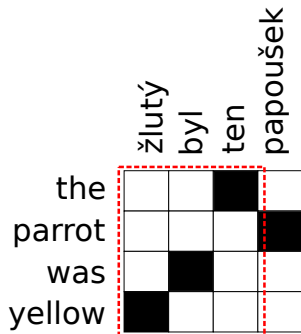
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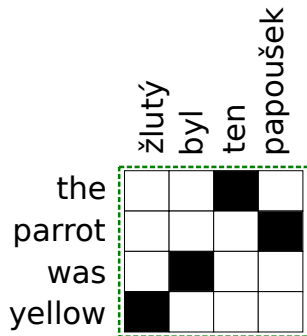
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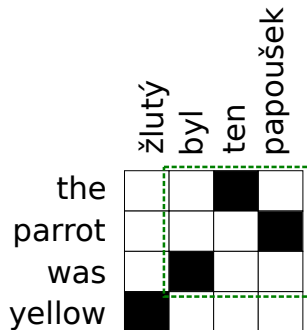
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Building a Phrase Table (Translation Model)

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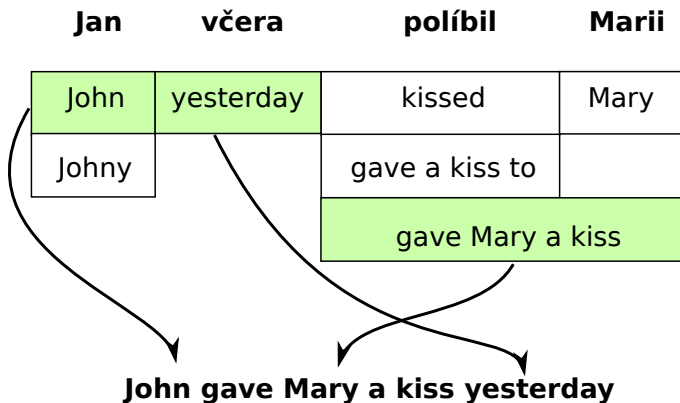
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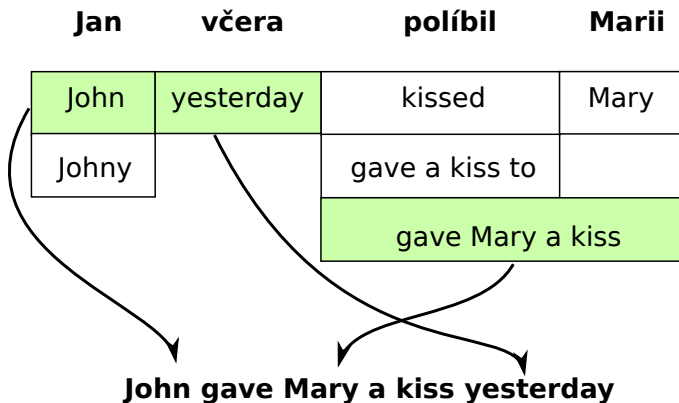
Tiny example:

```
žlutý papoušek ||| a yellow parrot ||| 0.1  
žlutý papoušek ||| yellow parakeet ||| 0.1  
žlutý papoušek ||| yellow parrot ||| 0.6  
žlutý papoušek ||| yellowish parrot ||| 0.2
```

Progress Check



Progress Check



How do we decide which of these translations is best?

The Noisy Channel Model

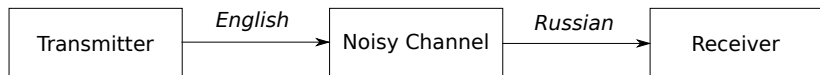
Warren Weaver (1955):

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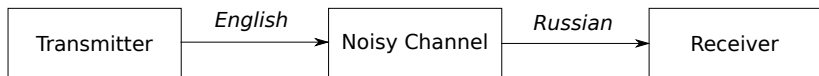
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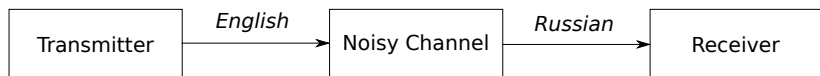


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$$\begin{aligned}\hat{e} &= \arg \max_e P(\mathbf{e}|\mathbf{f}) = \arg \max_e \frac{P(\mathbf{f}|\mathbf{e})P(\mathbf{e})}{P(\mathbf{f})} \\ &= \arg \max_e \underbrace{P(\mathbf{f}|\mathbf{e})}_{\text{Translation model}} \underbrace{P(\mathbf{e})}_{\text{Language model}}\end{aligned}$$

Noisy Channel Model

$$\hat{\mathbf{e}} = \arg \max_{\mathbf{e}} P(\mathbf{f}|\mathbf{e})P(\mathbf{e})$$

- $P(\mathbf{e})$ is the language model (LM).
- $P(\mathbf{f}|\mathbf{e})$ depends on the application:
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(Only requires monolingual data!)
- So far, we only talked about half of the story.
(And technically, in the wrong direction, given that we want to translate Czech into English.)

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- Let's formulate the n -gram LM:

$$\begin{aligned} P(\mathbf{e}) &= P(e_1)P(e_2|e_1)P(e_3|e_1, e_2) \dots P(e_{l_e}|e_1, \dots, e_{l_e-1}) \\ &\approx P(e_1)P(e_2|e_1) \dots P(e_{l_e}|e_{l_e-n+1}, \dots, e_{l_e-1}) \end{aligned}$$

Language Model: Example

A 3-gram language model (only depend on 2 previous words).

$$\begin{aligned} P(\text{"thank you very much"}) &= P(\text{"thank"} | \text{"<s>"}) \\ &\times P(\text{"you"} | \text{"<s>thank"}) \\ &\times P(\text{"very"} | \text{"thank you"}) \\ &\times P(\text{"much"} | \text{"you very"}) \end{aligned}$$

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Smoothing!

Log-Linear Model

Begin with the noisy channel model:

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We could add other features (besides LM and TM), so generally:

$$\hat{e} = \arg \max_e \sum_i \lambda_i f_i(\mathbf{e}, \mathbf{f})$$

Log-Linear Model: Features

We now have the freedom to add new features. In PBMT, we typically use:

- Phrase translation probability, both direct and inverse:
 - ▶ $P(\mathbf{e}|\mathbf{f})$
 - ▶ $P(\mathbf{f}|\mathbf{e})$
- Lexical translation probability (direct and inverse):
 - ▶ $P_{lex}(\mathbf{e}|\mathbf{f})$
 - ▶ $P_{lex}(\mathbf{f}|\mathbf{e})$
- Language model probability:
 - ▶ $P(\mathbf{e})$
- Phrase penalty.
- Word penalty.
- Distortion penalty.

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Is that a reliable probability estimate?

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Data from the “wild” are noisy. Word alignment contains errors.
This is a real phrase pair from our best English-Czech system.
Both $P(\mathbf{e}|\mathbf{f})$ and $P(\mathbf{f}|\mathbf{e})$ say that this is a perfect translation.

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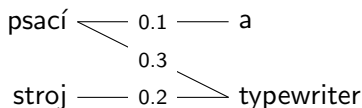
$$P_{lex}(\mathbf{e}|\mathbf{f}, a) = \prod_{j=1}^{l_e} \frac{1}{|\{i|(i,j) \in a\}|} \sum_{\forall (i,j) \in a} w(e_j, f_i)$$

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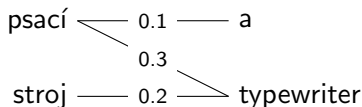


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$$P_{lex}(\text{"a typewriter"}|\text{"psací stroj"}) = \left[\frac{1}{1} \cdot 0.1 \right] \cdot \left[\frac{1}{2} \cdot (0.3 + 0.2) \right] = 0.025$$

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vidím problém ||| I can see a problem

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- Varying the λ for phrase penalty can lead to more literal (word-by-word) translations (made from a lot of short phrases) or to more idiomatic outputs (use fewer, longer phrases – if available).

Distortion Penalty

- The simplest way to capture **phrase reordering**.
- Can be sufficient for some language pairs (our English→Czech systems use it).
- Several possible definitions, e.g.:
 - ▶ Distance between the end of the previous phrase (on the source side) and the beginning of the current phrase.

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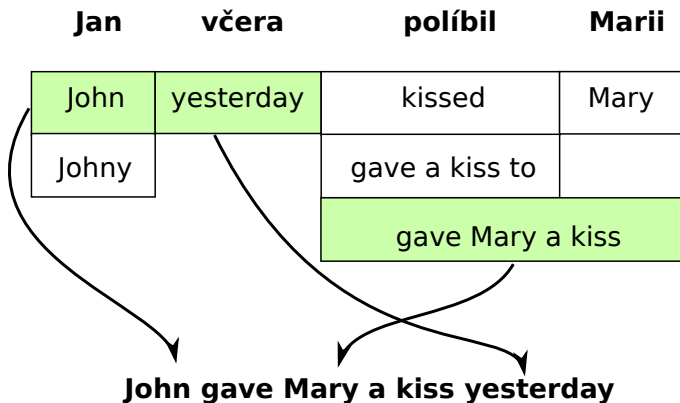
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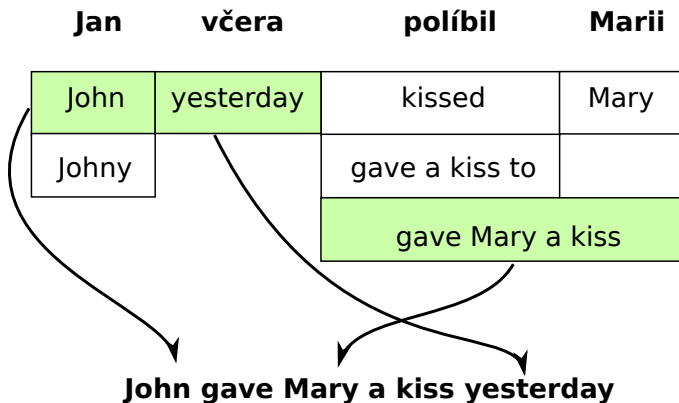
“Tuning”

- See the lecture tomorrow: Discriminative Training (Miloš Stanojević)

Progress Check



Progress Check



Search for the best translation.

Translation Process: Generate Translation Options

Jan	včera	políbil	Marii
John	yesterday	kissed	Mary
Johnty		gave a kiss to	
		gave Mary a kiss	

Translation Process: Beam Search

